## A NOTE ON PAIRWISE PIVOTING

Given a non-singular matrix

we want to perform Gaussian elimination to A on a machine with limited memory. Assuming that we are only allowed to store two rows in the working memory at a time. Then one way to include some form of pivoting will be as follows.

STEP 1. Compare the magnitude of the leading entries in the rows 1 and 2,

and choose the larger entry as the pivot.

STEP 2. Permute rows 1 and 2 accordingly to bring the larger entry into the pivoting position.

STEP 3. Eliminate the entry below the pivot

	$\square$	×	×	×	×	$\begin{array}{c} \times \\ \times \\ \times \\ \times \\ \times \\ \times \\ \times \end{array}$
$A^{(1)} =$	0	×	×	×	×	×
	×	×	×	×	×	$\times$
	×	×	×	×	×	$\times$
	×	$\times$	$\times$	$\times$	$\times$	$\times$
	×	×	×	×	×	$\times$

Notice that the elements in bold are now changed because of the row operation (unless, of course, if the entry below the pivot is 0 to begin with, then we don't do anything and proceed to the next stage).

STEP 4. Repeat STEP 1 through STEP 4 with rows 1 and 3 of the matrix

$A^{(1)} =$	$\square$	×	×	×	×	×
	0	Х	$\times$	×	$\times$	$\times$
	$\square$	$\times$	×	$\times$	$\times$	$\times$
	×	$\times$	×	×	×	$\times$
	×	$\times$	×	×	×	$\times$
	L×	Х	× × × × ×	×	Х	×

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to get

repeat until we have

$$A^{(n)} = \begin{bmatrix} \times & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \end{bmatrix}.$$

STEP 5. Now repeat STEPS 1 through STEPS 5 to the  $(n-1) \times (n-1)$  principal block  $A^{(n)}[2:n;2:n]$  to get

$$B^{(n)} = \begin{bmatrix} \times & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \end{bmatrix}.$$

STEP 6. Repeat until you get

$$U^{(n)} = \begin{bmatrix} \times & \times & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & 0 & 0 & \times & \times & \times \\ 0 & 0 & 0 & 0 & 0 & \times & \times \\ 0 & 0 & 0 & 0 & 0 & 0 & \times \end{bmatrix}.$$

In the homework, you are required to do this for *Gauss-Jordan elimination* instead of Gaussian elimination. The idea is similar but now you will need to eliminate the entry above the pivot in STEP 5:

$$B^{(n)} = \begin{bmatrix} \times & \boxtimes & \times & \times & \times & \times \\ 0 & \times & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \\ 0 & 0 & \times & \times & \times & \times \end{bmatrix}.$$

Comparing Gaussian elimination with pairwise pivoting and partial pivoting, you will quickly see that pairwise pivoting offers the following advantages:

- Pairwise pivoting avoids a search for a largest pivot down a column.
- As in partial pivoting, pairwise pivoting has the property that the multipliers are always bounded by 1.

• Pairwise pivoting permits greater parallelism. Observe that the following entries (labelled as n = (1, ..., (9)) can be eliminated simultaneously in the *n*th stage:

×	$\times$	$\times$	$\times$	$\times$	×	
1	$\times$	$\times$	$\times$	$\times$	Х	
2	3	×	×	$\times$	×	
3	4	(5)	×	$\times$	×	•
4	(5)	6	× ⑦	$\times$	×	
5	6	$\overline{O}$	8	9	×	

Your program does not need to exhibit this parallel feature.

Pairwise pivoting has some serious disadvantages too — most notably a  $4^n$  factor in the error bound. Another point is that while partial pivoting requires 1 row interchange to zero out all entries below a pivot, pairwise pivoting may take up to n row interchanges (STEP 2).