# STAT 309: MATHEMATICAL COMPUTATIONS I FALL 2022 LECTURE 1

## 1. NORMS

- a norm is a real-valued function on a vector space (over  $\mathbb{R}$  or  $\mathbb{C}$ ), denoted  $\|\cdot\|:V\to\mathbb{R}$  satisfying
  - (i)  $||v|| \ge 0$  for all  $v \in V$
  - (ii) ||v|| = 0 if and only if  $v = 0_V$
  - (iii)  $\|\alpha v\| = |\alpha| \|v\|$  for all  $\alpha \in \mathbb{C}$  and  $v \in V$
  - (iv)  $||v + w|| \le ||v|| + ||w||$  for any  $v, w \in V$
- the triangle inequality generalizes directly to sums of more than two vectors:

$$||u+v+w|| \le ||u+v|| + ||w|| \le ||u|| + ||v|| + ||w||$$

• more generally,

$$\left\| \sum_{i=1}^{m} v_i \right\| \le \sum_{i=1}^{m} \|v_i\|$$

- $\bullet$  we will be interested in two specific choices of V
  - $-V = \mathbb{R}^n \text{ or } \mathbb{C}^n$
  - $-V = \mathbb{R}^{m \times n}$  or  $\mathbb{C}^{m \times n}$

## 2. VECTOR NORMS

- if  $V = \mathbb{C}^n$  or  $V = \mathbb{R}^n$ , we call a norm on V a vector norm
- example: consider  $\|\cdot\|_1:\mathbb{C}^n\to\mathbb{R}$  defined by

$$\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$$

for  $\mathbf{x} = [x_1, \dots, x_n]^\mathsf{T} \in \mathbb{C}^n$  and where |x| denotes the modulus/absolute value of  $x \in \mathbb{C}$  – check that this is a norm:

- (1) clearly  $\|\mathbf{x}\|_1 \geq 0$
- (2) the only way a sum nonnegative entries  $\|\mathbf{x}\|_1 = 0$  is if all entries  $|x_i| = 0$  and so  $\mathbf{x} = [0, \dots, 0]^{\mathsf{T}} = \mathbf{0}$
- (3) we have

$$\|\alpha \mathbf{x}\|_1 = \sum_{i=1}^n |\alpha x_i| = |\alpha| \sum_{i=1}^n |x_i| = |\alpha| \|\mathbf{x}\|_1$$

since complex modulus satisfies  $|\alpha x| = |\alpha||x|$ 

(4) using the triangle inequality for complex numbers, we obtain

$$\|\mathbf{x} + \mathbf{y}\|_1 = \sum_{i=1}^n |x_i + y_i| \le \sum_{i=1}^n |x_i| + |y_i| \le \|\mathbf{x}\|_1 + \|\mathbf{y}\|_1$$

- therefore the function defines a norm, called the 1-norm or Manhattan norm

• example: more generally, for  $p \geq 1$  (can be any real number, not necessarily an integer), we define the p-norm  $\|\mathbf{x}\|_p$  by

$$\|\mathbf{x}\|_p = (|x_1|^p + \dots + |x_n|^p)^{1/p}$$

- most commonly used p-norms is the 2-norm or Euclidean norm:

$$\|\mathbf{x}\|_2 = \left(\sum_{i=1}^n |x_i|^2\right)^{1/2}$$

- easy to see that for any p, we have

$$\left(\max_{i=1,\dots,n} |x_i|^p\right)^{1/p} \le \|\mathbf{x}\|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p} \le \left(n\max_{i=1,\dots,n} |x_i|^p\right)^{1/p}$$

- from which it follows that

$$\max_{i=1,\dots,n} |x_i| \le ||\mathbf{x}||_p \le n^{1/p} \max_{i=1,\dots,n} |x_i|$$

- as  $p \to \infty$ , we obtain the *infinity norm* 

$$\|\mathbf{x}\|_{\infty} = \lim_{p \to \infty} \|\mathbf{x}\|_p = \max_{i=1,\dots,n} |x_i|$$

which is also known as the Chebyshev norm

- easy to verify that p-norms for any  $p \in [1, \infty]$  are indeed norms
- generalization of the p-norm is the weighted p-norm, defined by

$$\|\mathbf{x}\|_{p,\mathbf{w}} = \left(\sum_{i=1}^n w_i |x_i|^p\right)^{1/p}$$

- again it can be shown that this is a norm as long as the weights  $w_i$ ,  $i=1,\ldots,n$ , are strictly positive real numbers
- example: a vast generalization of all of the above is the A-norm or Mahalanobis norm, defined in terms of a matrix A by

$$\|\mathbf{x}\|_{A} = (\mathbf{x}^* A \mathbf{x})^{1/2} = \left(\sum_{i,j=1}^{n} a_{ij} \overline{x}_i x_j\right)^{1/2}$$

- this defines a norm provided that the matrix A is positive definite
- note that if  $W = \operatorname{diag}(\mathbf{w})$ , then

$$\|\mathbf{x}\|_W = \|\mathbf{x}\|_{2,\mathbf{w}}$$

# 3. Matrix norms

- note that the space of complex  $m \times n$  matrices  $\mathbb{C}^{m \times n}$  is a vector space over  $\mathbb{C}$  (ditto for real matrices over  $\mathbb{R}$ ) of dimension mn
- we write O for the  $m \times n$  zero matrix, i.e., all entries are 0
- a norm on either  $\mathbb{C}^{m\times n}$  or  $\mathbb{R}^{m\times n}$  is called a matrix norm
- recall that these means  $\|\cdot\|:\mathbb{C}^{m\times n}\to\mathbb{R}$  satisfies
  - (1)  $||A|| \ge 0$  for all  $A \in \mathbb{C}^{m \times n}$
  - (2) ||A|| = 0 if and only if A = O
  - (3)  $\|\alpha A\| = |\alpha| \|A\|$
  - $(4) ||A + B|| \le ||A|| + ||B||$
- often we add a fifth condition that  $\|\cdot\|$  satisfies the submultiplicative property

$$||AB|| \le ||A|| ||B||$$

#### 4. HÖLDER NORMS

• example: Frobenius norm

$$||A||_{\mathsf{F}} = \left(\sum_{i=1}^{m} \sum_{j=1}^{n} |a_{ij}|^2\right)^{1/2}$$

which is submultiplicative since

$$||AB||_{\mathsf{F}}^2 = \sum_{i=1}^m \sum_{k=1}^p \left| \sum_{j=1}^n a_{ij} b_{jk} \right|^2 \le \sum_{i=1}^m \sum_{k=1}^p \left[ \left( \sum_{j=1}^n |a_{ij}|^2 \right) \left( \sum_{j=1}^n |b_{jk}|^2 \right) \right]$$

by the Cauchy-Schwarz inequality and the last expression is equal to

$$\left(\sum_{i=1}^{m} \sum_{j=1}^{n} |a_{ij}|^2\right) \left(\sum_{k=1}^{p} \sum_{j=1}^{n} |b_{jk}|^2\right) = \|A\|_{\mathsf{F}}^2 \|B\|_{\mathsf{F}}^2$$

• example: more generally we have Hölder p-norm for any  $p \in [1, \infty]$ ,

$$||A||_{H,p} = \left(\sum_{i=1}^{m} \sum_{j=1}^{n} |a_{ij}|^p\right)^{1/p}$$

and

$$||A||_{H,\infty} = \max_{i,j} |a_{ij}|$$

- Hölder norms are obtained by viewing an  $m \times n$  matrix  $A = [a_{ij}]_{i,j=1}^{m,n} \in \mathbb{C}^{m \times n}$  as a vector  $\boldsymbol{\alpha} = [a_{11}, a_{12}, \dots, a_{mn}]^{\mathsf{T}} \in \mathbb{C}^{mn}$  with mn entries, this is often written as

$$\alpha = \text{vec}(A)$$

- we have  $||A||_{H,p} = ||\operatorname{vec}(A)||_p$
- clearly  $||A||_{H,2} = ||A||_{\mathsf{F}} = ||\operatorname{vec}(A)||_2$
- in general Hölder p-norms are not submultiplicative for  $p \neq 2$ 
  - example: take

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \qquad B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \qquad AB = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

but

$$||AB||_{H,\infty} = 2 > 1 = ||A||_{H,\infty} ||B||_{H,\infty}$$

## 5. OPERATOR NORMS

• a very important class of matrix norms are the so called *operator* or *induced* or *natural* norms defined as

$$||A||_{a,b} := \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_b}{||\mathbf{x}||_a} \tag{1}$$

for any  $A \in \mathbb{C}^{m \times n}$  and any vector norms  $\|\cdot\|_a : \mathbb{C}^n \to \mathbb{R}$  and  $\|\cdot\|_b : \mathbb{C}^m \to \mathbb{R}$  defined on the domain and codomain of A respectively

• the operator norm may also be written as

$$||A||_{a,b} = \max\{||A\mathbf{x}||_b : ||\mathbf{x}||_a \le 1\}$$
(2)

or as

$$||A||_{a,b} = \max\{||A\mathbf{x}||_b : ||\mathbf{x}||_a = 1\}$$
(3)

- in other words, the operator norm measures how far the operator A sends points in the unit disc (or the unit circle)
- proof is simple, for example, here's how you would prove (3):

$$\max_{\mathbf{x} \neq \mathbf{0}} \frac{\|A\mathbf{x}\|_b}{\|\mathbf{x}\|_a} = \max_{\mathbf{x} \neq \mathbf{0}} \left\| \frac{1}{\|\mathbf{x}\|_a} A\mathbf{x} \right\|_b = \max_{\mathbf{x} \neq \mathbf{0}} \left\| A \left( \frac{\mathbf{x}}{\|\mathbf{x}\|_a} \right) \right\|_b = \max_{\|\mathbf{v}\|_a = 1} \left\| A\mathbf{v} \right\|_b,$$

the first equality uses the property that  $|\alpha| \|\mathbf{v}\|_b = \|\alpha \mathbf{v}\|_b$ , the second equality uses  $\alpha A \mathbf{x} = A(\alpha \mathbf{x})$ , and the last equality uses the observation that  $\mathbf{v} = \mathbf{x}/\|\mathbf{x}\|_a$  always has unit a-norm

- exercise: prove (3) and (2) are equal
- another exercise: prove that

$$||A\mathbf{x}||_b \le ||A||_{a,b} ||\mathbf{x}||_a \tag{4}$$

for any  $\mathbf{x} \in \mathbb{C}^n$ ; this more restrictive form of submultiplicativity is called *consistency* 

- a note on the use of supremum and maximum: for  $S \subseteq \mathbb{C}^n$  and a real-valued function f whose domain includes S,
  - we write  $\sup_{\mathbf{x}\in S} f(\mathbf{x})$  for the smallest  $\mu\in\mathbb{R}$  such that  $f(\mathbf{x})\leq\mu$  for every  $\mathbf{x}\in S$  (and we set  $\mu=+\infty$  if f is unbounded on S)
  - we write  $\max_{\mathbf{x} \in S} f(\mathbf{x})$  if the supremum is attained by some element in S, i.e., there is an  $\mathbf{x}_{\max} \in S$  such that  $f(\mathbf{x}_{\max}) = \sup_{\mathbf{x} \in S} f(\mathbf{x})$
  - $-\mathbf{x}_{\text{max}}$  is called a maximizer of f on S
  - likewise for infimum and minimum (and minimizer)
  - by the extreme value theorem, if f is continuous and S is compact, then supremum and infimum are always attained
- in the above  $S = \{ \mathbf{x} \in \mathbb{C} : ||\mathbf{x}||_a \le 1 \}$  and  $S = \{ \mathbf{x} \in \mathbb{C} : ||\mathbf{x}||_a = 1 \}$  are compact and the function  $f = ||\cdot||_b : \mathbb{C}^m \to \mathbb{R}$  is continuous
- in other words, we can always find an  $\mathbf{x}_{\text{max}}$  with  $\|\mathbf{x}_{\text{max}}\|_a = 1$  such that

$$||A\mathbf{x}_{\max}||_b = ||A||_{a,b}$$

• that's why we may always write max in (3) and (2), and therefore in (1); although strictly speaking we should have written (1)

$$||A||_{a,b} := \sup_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_b}{||\mathbf{x}||_a}$$

• the operator norm is *not* submultiplicative in general: take

$$A = \begin{bmatrix} 2 & 2 \\ 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$$

since every  $\mathbf{x} \in \mathbb{R}^2$  with  $\|\mathbf{x}\| = 1$  has the form  $\mathbf{x} = (\cos \theta, \sin \theta)^{\mathsf{T}}$ , we see that

$$||A||_{2,\infty} = \max_{\|\mathbf{x}\|_2 = 1} ||A\mathbf{x}||_{\infty} = \max_{\theta} |2\cos\theta + 2\sin\theta| = 2\sqrt{2}$$
$$||B||_{2,\infty} = \max_{\|\mathbf{x}\|_2 = 1} ||B\mathbf{x}||_{\infty} = \max_{\theta} |\cos\theta| = 1$$
$$||AB||_{2,\infty} = \max_{\|\mathbf{x}\|_2 = 1} ||AB\mathbf{x}||_{\infty} = \max_{\theta} |4\cos\theta| = 4$$

but

$$||AB||_{2,\infty} = 4 > 2\sqrt{2} = ||A||_{2,\infty} ||B||_{2,\infty}$$

(thanks to Lijun Ding for this example)

• however given  $A \in \mathbb{C}^{m \times n}$  and  $B \in \mathbb{C}^{n \times p}$  it is always true that

$$||AB||_{a,c} \le ||A||_{b,c} ||B||_{a,b}$$

for any norms  $\|\cdot\|_c$  on  $\mathbb{C}^p$ ,  $\|\cdot\|_b$  on  $\mathbb{C}^m$ ,  $\|\cdot\|_a$  on  $\mathbb{C}^n$ 

• the most interesting operator norms are the ones obtained when  $\|\cdot\|_a$  and  $\|\cdot\|_b$  are vector  $\ell^p$ -norms, we write

$$||A||_{p,q} \coloneqq \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_q}{||\mathbf{x}||_p} \quad \text{and} \quad ||A||_p \coloneqq \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_p}{||\mathbf{x}||_p}$$

for any  $A\in\mathbb{C}^{m\times n}$  and  $p,q\in[1,\infty]$ 

- we call  $\|\cdot\|_{p,q}$  the matrix (p,q)-norm and  $\|\cdot\|_p$  the matrix p-norm
- the matrix 2-norm

$$||A||_2 = \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_2}{||\mathbf{x}||_2}$$

is very widely used and has its own special name, spectral norm, because of its relation to the spectrum of a matrix (i.e., the eigenvalues); we will discuss it in the next two lectures

- the matrix 1-norm and  $\infty$ -norm are also very widely used, largely because, they can be easily computed
- let  $A = [a_{ij}]_{i,j=1}^{m,n} \in \mathbb{C}^{m \times n}$ , then

$$||A||_1 = \max_{j=1,\dots,n} \left[ \sum_{i=1}^m |a_{ij}| \right]$$
 (5)

and

$$||A||_{\infty} = \max_{i=1,\dots,m} \left[ \sum_{j=1}^{n} |a_{ij}| \right]$$
 (6)

- an easy way to remember these is that  $||A||_1$  is the maximum column sum and  $||A||_{\infty}$  is the maximum row sum of A
- let us prove (6) and leave (5) as an exercise:
  - we use (3), so

$$||A||_{\infty} = \max\{||A\mathbf{x}||_{\infty} : ||\mathbf{x}||_{\infty} = 1\}$$

$$= \max_{\|\mathbf{x}\|_{\infty} = 1} \left\{ \max_{i=1,\dots,m} \left| \sum_{j=1}^{n} a_{ij} x_{j} \right| \right\}$$

$$\leq \max_{\|\mathbf{x}\|_{\infty} = 1} \left\{ \max_{i=1,\dots,m} \left[ \sum_{j=1}^{n} |a_{ij}| |x_{j}| \right] \right\}$$

$$\leq \max_{i=1,\dots,m} \left[ \sum_{j=1}^{n} |a_{ij}| \right]$$
(7)

where the last inequality follows because  $\|\mathbf{x}\|_{\infty} = 1$  and so we must have  $|x_j| \leq 1$  – to show equality, we just need to exhibit one single  $\mathbf{x}^*$  with  $\|\mathbf{x}^*\|_{\infty} = 1$  so that

$$||A\mathbf{x}^*||_{\infty} \ge \max_{i=1,\dots,m} \left[ \sum_{j=1}^n |a_{ij}| \right]$$

- we know that the maximum in (7) is attained by some row  $i = k \in \{1, ..., m\}$ , so

$$\max_{i=1,\dots,m} \left[ \sum_{j=1}^{n} |a_{ij}| \right] = \sum_{j=1}^{n} |a_{kj}|$$

– now we define  $\mathbf{x}^* = [x_1^*, \dots, x_n^*] \in \mathbb{C}^n$  as the vector whose coordinates are given by

$$x_j^* = \begin{cases} |a_{kj}|/a_{kj} & \text{if } a_{kj} \neq 0, \\ 0 & \text{if } a_{kj} = 0, \end{cases}$$

for  $j = 1, \dots, n$ 

– observe that  $\mathbf{x}^*$  has  $\|\mathbf{x}^*\|_{\infty} = 1$  as well as the effect of attaining the requisite bound

$$||A\mathbf{x}^*||_{\infty} = \max_{i=1,\dots,m} \left| \sum_{j=1}^n a_{ij} x_j^* \right| \ge \sum_{j=1}^n |a_{kj}| = \max_{i=1,\dots,m} \left[ \sum_{j=1}^n |a_{ij}| \right]$$