

Optimal rates of sparse estimation and universal aggregation

Philippe Rigollet



Princeton University

with A. Tsybakov (Paris VI and CREST)



Prologue: sparsity in linear model

- $\mathbf{Y} = \mathbf{X}\theta + \xi$, standard normal ξ .
- $\dim \theta = M \gg n = \text{sample size}$.
- The Lasso estimator $\hat{\theta}_L$ w.p. close to 1 satisfies:

$$|\mathbf{X}(\hat{\theta}_L - \theta)|_2^2/n \leq C|\theta|_0 \frac{\log M}{n}, \quad \text{restrictive assumptions on } \mathbf{X}.$$

$$|\mathbf{X}(\hat{\theta}_L - \theta)|_2^2/n \leq C|\theta|_1 \sqrt{\frac{\log M}{n}}, \quad \text{NO assumption on } \mathbf{X}.$$

Here $|\cdot|_p, p \geq 1$ is the ℓ_p norm, $|\theta|_0 = \text{number of non-zero components of } \theta$.

- **Question:** How optimal are these bounds?



Setup

- Regression with **fixed** design.
- We observe

$$Y_i = \eta(x_i) + \xi_i, \quad i = 1, \dots, n$$

- where:
 - $\eta : \mathcal{X} \rightarrow \mathbb{R}$ is the unknown regression function,
 - $x_i, i = 1, \dots, n$ are known deterministic points in \mathcal{X} ,
 - $\xi_i, i = 1, \dots, n$ are i.i.d $\mathcal{N}(0, \sigma^2)$, σ^2 known.
- Performance of an estimator $\hat{\eta}$

$$\|\hat{\eta} - \eta\|^2 = \frac{1}{n} \sum_{i=1}^n [\hat{\eta}(x_i) - \eta(x_i)]^2 \quad (\text{MSE})$$



Aggregation

- Given a **dictionary** $\mathcal{H} = \{f_1, \dots, f_M\}$, $f_j : \mathcal{X} \rightarrow \mathbb{R}$,
- we are interested in finding the **best linear combination** of the f_j 's:

$$\mathbf{f}_\theta = \sum_{j=1}^M \theta_j f_j, \quad \theta \in \mathbb{R}^M$$

- More precisely we want to find $\hat{\eta}$ such that

$$\mathbb{E} \|\hat{\eta} - \eta\|^2 = \min_{\theta \in \mathbb{R}^M} \|\mathbf{f}_\theta - \eta\|^2$$

is as small as possible.



Oracle inequalities

- Upper bounds for the risk of (linear) aggregation are presented as oracle inequalities of the form

$$\mathbb{E}\|\hat{\eta} - \eta\|^2 \leq (1 + \varepsilon) \min_{\theta \in \mathbf{R}^M} \|\mathbf{f}_\theta - \eta\|^2 + \Delta_{n,M},$$

- We are interested specifically in the case $\varepsilon = 0$ (exact oracle inequalities).
- The smallest possible remainder term $\Delta_{n,M}$ (optimal rate of linear aggregation)

$$\Delta_{M,n} = \mathcal{O}\left(\frac{M}{n}\right)$$

and is attained by least squares.



Sparse oracle inequalities

- For good approximation properties: $M \gg n$ so the rate $\frac{M}{n}$ is useless.
- Solution: assume **sparsity**.
- Sparse Oracle Inequality (SOI):

$$\mathbb{E}\|\hat{\eta} - \eta\|^2 \leq \min_{\theta \in \mathbb{R}^M} \{ \|f_{\theta} - \eta\|^2 + \Delta_{n,M}(\theta) \} ,$$

where $\Delta_{n,M}(\theta)$ is smaller for “sparser” θ .

- Notice that the oracle $\theta^* = \operatorname{argmin}_{\theta} \|f_{\theta} - \eta\|^2$ need not be sparse. Only the best **balance** between the two terms (approximation and remainder) matters.



Outline

Sparse oracle inequalities when $M \gg n$

Sparsity pattern aggregation

Exponential screening

Optimality

Universal aggregation

Implementation and numerical illustration



Sparsity patterns

- A sparsity pattern is a vector $\mathbf{p} \in \{0, 1\}^M$.
- Define the set $\mathbb{R}^{\mathbf{p}}$ of vectors with sparsity pattern \mathbf{p} as

$$\mathbb{R}^{\mathbf{p}} = \{\theta \cdot \mathbf{p} : \theta \in \mathbb{R}^M\} \subset \mathbb{R}^M,$$

where $\theta \cdot \mathbf{p} \in \mathbb{R}^M$ denotes the Hadamard product.

- For any $\mathbf{p} \in \{0, 1\}^M$ define the least squares estimator

$$\hat{\theta}_{\mathbf{p}} \in \operatorname{argmin}_{\theta \in \mathbb{R}^{\mathbf{p}}} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2,$$

where

$$\mathbf{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix}, \quad \mathbf{X} = \begin{pmatrix} f_1(x_1) & \dots & f_M(x_1) \\ \vdots & & \vdots \\ f_1(x_n) & \dots & f_M(x_n) \end{pmatrix}$$



Sparsity pattern aggregation

- A first simple oracle inequality gives

$$\mathbb{E} \|\mathbf{f}_{\hat{\theta}_p} - \eta\|^2 \leq \min_{\theta \in \mathbb{R}^p} \|\mathbf{f}_\theta - \eta\|^2 + \sigma^2 \frac{|\mathbf{p}|_1 \wedge R}{n}$$

where $R = \text{rank}(\mathbf{X})$.

- $M \gg n$: $\frac{M}{n}$ is useless but $\frac{|\mathbf{p}|_1 \wedge R}{n}$ can be good \rightsquigarrow which \mathbf{p} to choose?
- Define the **sparsity pattern aggregate** $\tilde{\theta}^{\text{SPA}}$ by

$$\tilde{\theta}^{\text{SPA}} := \sum_{\mathbf{p} \in \{0,1\}^M} \hat{\theta}_p \nu_p,$$

where $\nu = (\nu_p)_p$ is a probability measure on $\{0, 1\}^M$.



Exponential screening

- To choose ν , we should downweight sparsity patterns with large SSE and large $|\mathbf{p}|_1$.
- Define the probability measure

$$\nu_{\mathbf{p}} \propto \exp\left(-\frac{1}{4\sigma^2} \sum_{i=1}^n (Y_i - \mathbf{f}_{\hat{\theta}_{\mathbf{p}}}(x_i))^2 - \frac{|\mathbf{p}|}{2}\right) \left(\frac{|\mathbf{p}|_1}{2eM}\right)^{|\mathbf{p}|_1} I(|\mathbf{p}|_1 \leq R)$$

- The SPA with this ν : **Exponential screening** $\tilde{\theta}^{\text{ES}}$.
- George (86), Leung & Barron (06), Giraud (08), Alquier & Lounici (10): exponential weighting with other initial estimators or other discrete priors. Dalalyan & Tsybakov. (07,08,09): exponential weighting with continuous priors.



Sparsity in terms of ℓ_1 norm

- Several methods based on ℓ_1 penalization (Lasso, Dantzig) are very efficient.
- SOI for those measure sparsity in terms of ℓ_1 norm (as opposed to ℓ_0 -norm).
- Becomes an advantage if $|\theta|_1 \ll |\theta|_0$ (many small coefficients, power decay, ...).
- Exponential screening adapts to **both** measures of sparsity.



Sparsity oracle inequality for ES

Theorem 1

For any $M \geq 1, n \geq 1$, if $\max_j \|f_j\| \leq 1$,

$$\begin{aligned} \mathbb{E} \|\mathbf{f}_{\tilde{\theta}^{\text{ES}}} - \eta\|^2 &\leq \min_{\theta \in \mathbb{R}^M} \{ \|\mathbf{f}_\theta - \eta\|^2 + \varphi_{n,M}(\theta) \} \\ &\quad + \frac{\sigma^2}{n} (9 \log(1 + eM) + 4 \log 2) \end{aligned}$$

where the remainder term $\varphi_{n,M}(\theta)$ is equal to

$$\frac{9\sigma^2 \widetilde{M}(\theta)}{n} \log \left(\frac{eM}{\widetilde{M}(\theta) \vee 1} \right) \wedge \frac{11\sigma|\theta|_1}{\sqrt{n}} \sqrt{\log \left(1 + \frac{3eM\sigma}{|\theta|_1 \sqrt{n}} \right)}.$$

where $\widetilde{M}(\theta) := \min(|\theta|_0, R)$.

Moreover, if $\eta = \mathbf{f}_{\theta^*}$, we can take $\varphi_{n,M}(\theta^*) \wedge |\theta^*|_1^2$ in the remainder term.



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Discussion

One and the same estimator takes advantage of three types of sparsity:

- small number of non-zero entries of θ (ℓ_0 norm)
- small global weight (ℓ_1 norm)
- small rank of the matrix \mathbf{X}



Related results

- SOI have been obtained by Bickel *et al.* (09), Bunea *et al.* (07, 07), Candes & Tao (07), Koltchinskii (08, 09, 09), van de Geer (08), Zhang & Huang (08), Zhang (09), ... (other references in those papers).
- Most of those results have the term $(1 + \varepsilon)$, $\varepsilon > 0$ in front of RHS.
- They deal with only one measure of sparsity (either $|\theta|_0$ or $|\theta|_1$) at a time.
- The rates there are slower than in Theorem 1.
- SOI of Theorem 1 holds with **no assumption on the dictionary**.



Minimax lower bounds

- We want to prove that $\psi_{n,M}(\theta) = \varphi_{n,M}(\theta) \wedge |\theta|_1^2$ is optimal in a minimax sense.
- Define the rate function

$$\zeta_{n,M}(S, \delta) = \frac{\sigma^2 S}{n} \log \left(1 + \frac{eM}{S} \right) \wedge \frac{\sigma \delta}{\sqrt{n}} \sqrt{\log \left(1 + \frac{eM\sigma}{\delta \sqrt{n}} \right)} \wedge \delta^2$$

↪ $\zeta_{n,M}(S, \delta) = \psi_{n,M}(\theta)$ with $\widetilde{M}(\theta) = S$ and $|\theta|_1 = \delta$.



Minimax lower bound on the intersection of ℓ_0 and ℓ_1 balls

Theorem 3

There exists a large class of dictionaries such that for any estimator T_n , possibly depending on δ, S, n, M, R and \mathcal{H} , there exists a numerical constant $c^* > 0$, such that

$$\sup_{\eta} \sup_{\substack{\theta \in \mathbb{R}_+^M \setminus \{0\} \\ M(\theta) \leq S \\ |\theta|_1 \leq \delta}} \{E_{\eta} \|T_n - \eta\|^2 - \|\mathbf{f}_{\theta} - \eta\|^2\} \geq c^* \kappa \zeta_{n,M}(S \wedge R, \delta),$$

where \mathbb{R}_+^M is the positive cone of \mathbb{R}^M .

Least favorable dictionaries satisfy a weak version of restricted isometry (RI) property.



Comparison with asymptotic bounds

- Donoho and Johnstone (92, 94), Abramovich et al. (06)
 - **diagonal model**: $M = n$, $\mathbf{X}^\top \mathbf{X}/n = I$,
 - **asymptotics** as $n \rightarrow \infty$ of the minimax risk on ℓ_p ball $B_p(a)$ with radius a .
- Cases: $p = 0$ and $p = 1$. **Asymptotic** minimax rate

$$\inf_{\hat{\theta}} \sup_{\theta \in B_0(S)} \mathbb{E} |\mathbf{X}(\hat{\theta} - \theta)|_2^2 / n \sim 2\sigma^2 \frac{S}{n} \log \left(\frac{n}{S} \right)$$

$$\inf_{\hat{\theta}} \sup_{\theta \in B_1(\delta)} \mathbb{E} |\mathbf{X}(\hat{\theta} - \theta)|_2^2 / n \sim \frac{\delta\sigma}{\sqrt{n}} \sqrt{2 \log \left(\frac{\sigma\sqrt{n}}{\delta} \right)} \wedge \delta^2$$

- Raskutti et al. (09): $M \neq n$, **asymptotic** rates $\frac{S}{n} \log \left(\frac{M}{S} \right)$ and $\delta \sqrt{\frac{\log M}{n}}$. Non-asymptotic effects wiped out.



Universal aggregation

- Given $\Theta \subset \mathbb{R}^M$, the goal of aggregation is to construct $\hat{\eta}$ such that

$$\mathbb{E}\|\hat{\eta} - \eta\|^2 \leq \min_{\theta \in \Theta} \|\mathbf{f}_\theta - \eta\|^2 + C\Delta_{n,M}(\Theta), \quad C > 0,$$

- Different choices of Θ have been proposed and studied by Nemirovskii (00), Tsybakov (03), Bunea *et al.* (07) and Lounici (07).
- Optimal rates of aggregations were obtained by Bunea *et al.* (07) where they showed that the BIC estimator satisfies

$$\mathbb{E}\|\mathbf{f}_{\hat{\theta}_{\text{BIC}}} - \eta\|^2 \leq (1 + a) \min_{\theta \in \Theta} \|\mathbf{f}_\theta - \eta\|^2 + C\frac{1 + a}{a^2}\Delta_{n,M}$$

- We call this **universal aggregation** (one estimator for all problems).



Different types of aggregation

$$\mathbb{E}\|\hat{\eta} - \eta\|^2 \leq \min_{\theta \in \Theta} \|\mathbf{f}_\theta - \eta\|^2 + C\Delta_{n,M}(\Theta), \quad C > 0,$$

Problem	Θ	Description
(MS)	$\Theta_{(\text{MS})} = \{e_1, \dots, e_M\}$	Best in dictionary
(C)	$\Theta_{(\text{C})} = B_1(1)$	Best convex comb.
(L)	$\Theta_{(\text{L})} = \mathbb{R}^M$	Best linear comb.
(L _D)	$\Theta_{(\text{L}_D)} = B_0(D)$	Best D -sparse linear comb.
(C _D)	$\Theta_{(\text{C}_D)} = B_0(D) \cap B_1(1)$	Best D -sparse convex comb.

[Bunea *et al.* (07)]



ES solves all aggregation problems

Theorem 3

Assume that $\max_{1 \leq j \leq M} \|f_j\| \leq 1$. Then for any $M \geq 2, n \geq 1, D \leq M$, and $\Theta \in \{\Theta_{(\text{MS})}, \Theta_{(\text{C})}, \Theta_{(\text{L})}, \Theta_{(\text{L}_D)}, \Theta_{(\text{C}_D)}\}$ the Exponential Screening estimator satisfies the following oracle inequality

$$\mathbb{E} \|\mathbf{f}_{\hat{\theta}^{\text{ES}}} - \eta\|^2 \leq \min_{\theta \in \Theta} \|\mathbf{f}_{\theta} - \eta\|^2 + C \Delta_{n,M}^*(\Theta),$$

where $C > 0$ is a numerical constant and $\Delta_{n,M}^*(\Theta)$ is the optimal rate of aggregation on Θ given on the next slide.



Optimal rates of aggregation $\Delta_{n,M}^*(\Theta)$

A refinement of the rates with R and σ gives

Problem	$\Delta_{n,M}^*(\Theta)$
(MS)	$\frac{\sigma^2 \log M}{n}$
(C)	$\sqrt{\frac{\sigma^2}{n} \log \left(1 + \frac{eM\sigma}{\sqrt{n}}\right)} \wedge \frac{\sigma^2(M \wedge R)}{n} \log \left(1 + \frac{eM}{M \wedge R}\right)$
(L)	$\frac{\sigma^2(M \wedge R)}{n} \log \left(1 + \frac{eM}{M \wedge R}\right)$
(L _D)	$\frac{\sigma^2(D \wedge R)}{n} \log \left(1 + \frac{eM}{D \wedge R}\right)$
(C _D)	$\sqrt{\frac{\sigma^2}{n} \log \left(1 + \frac{eM\sigma}{\sqrt{n}}\right)} \wedge \frac{\sigma^2(D \wedge R)}{n} \log \left(1 + \frac{eM}{D \wedge R}\right)$



Metropolis-Hastings algorithm

- Recall that the ES estimator $\tilde{\theta}^{\text{ES}}$ is:

$$\tilde{\theta}^{\text{ES}} = \sum_{\mathbf{p} \in \{0,1\}^M} \hat{\theta}_{\mathbf{p}} \nu_{\mathbf{p}}$$

- Virtually 2^M least squares estimators to compute.
- Overcome by finding a Markov chain on the vertices $\{0, 1\}^M$ and with stationary distribution

$$\nu_{\mathbf{p}} \propto \exp\left(-\frac{1}{4\sigma^2} \sum_{i=1}^n (Y_i - f_{\hat{\theta}_{\mathbf{p}}}(x_i))^2\right) \left(\frac{|\mathbf{p}|_1}{2eM}\right)^{|\mathbf{p}|_1} I(|\mathbf{p}|_1 \leq R)$$

- We use the uniform proposal but can be improved for faster convergence.



Convergence of the Metropolis-Hastings algorithm

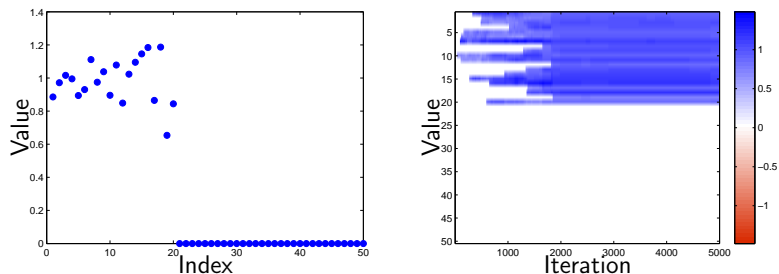


Figure: Typical realization for $(M, n, S) = (500, 200, 20)$. *Left:* Value of the $\tilde{\theta}_T^{\text{ES}}$, $T = 7,000$, $T_0 = 3,000$. *Right:* Value of iterate for $t = 1, \dots, 5000$. Only the first 50 coordinates are shown for each vector.



Prediction under restricted isometry

- Compare our results in a sparse recovery setting, i.e., when RI property is satisfied.
- Consider the model $\mathbf{Y} = \mathbf{X}\theta^* + \sigma\xi$ where
 1. \mathbf{X} is an $n \times M$ matrix with independent Rademacher entries
 2. $\xi \in \mathbb{R}^n$ is a vector of independent standard Gaussian random variables and is independent of \mathbf{X}
 3. $\theta_j^* = \mathbb{I}(j \leq S)$ for some fixed S so that $M(\theta^*) = S$
 4. $\sigma^2 = S/9$
- We consider the **prediction error**

$$|\mathbf{X}(\hat{\theta} - \theta^*)|_2^2/n = \|\mathbf{f}_{\hat{\theta}} - \mathbf{f}_{\theta^*}\|^2.$$

(Setup of Candes & Tao (07))



Results

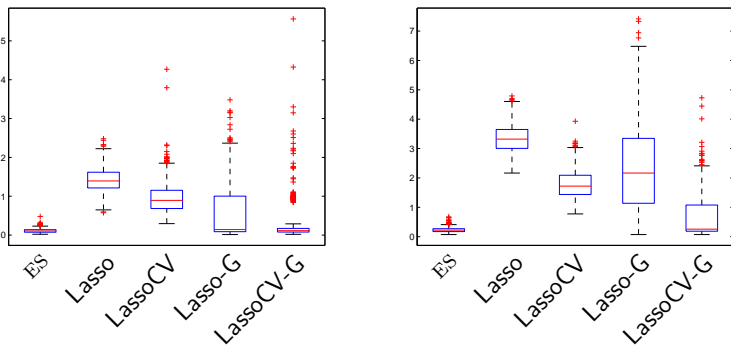
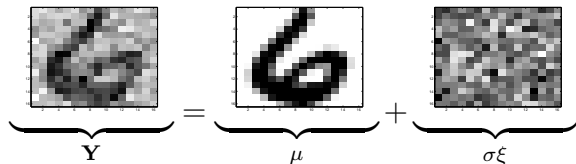


Figure: Boxplots of $|\mathbf{X}(\hat{\theta} - \theta^*)|_2^2/n$ over 500 realizations for the ES, Lasso, cross-validated Lasso (LassoCV), Lasso-Gauss (Lasso-G) and cross-validated Lasso-Gauss (LassoCV-G) estimators. *Left:* $(n, M, S) = (100, 200, 10)$, *right:* $(n, M, S) = (200, 500, 20)$.



Reconstruction of the digit "6"

- Difficult to actually find \mathbf{X} which does not satisfy RI condition and with $M \gg n$.
- Solution: handwritten digit dataset of LeCun *et al.* (90). Consists of 256 pixels grayscale images.
- Idea: take one image + noise to be \mathbf{Y} in \mathbb{R}^{256} and the dictionary to be the remaining 7,290 images.
- Formally



The diagram illustrates the equation $\mathbf{Y} = \mu + \sigma\xi$. It consists of three square grayscale images arranged horizontally, separated by an equals sign and a plus sign. The first image, labeled \mathbf{Y} below it, shows a handwritten digit '6' that is heavily obscured by random noise. The second image, labeled μ below it, shows the same handwritten digit '6' but is clean and clear. The third image, labeled $\sigma\xi$ below it, shows a square of random noise. Brackets are placed under each image to indicate the labels.

- We try to approximate μ with linear combinations of the other images in the dataset.



Correlated dictionary

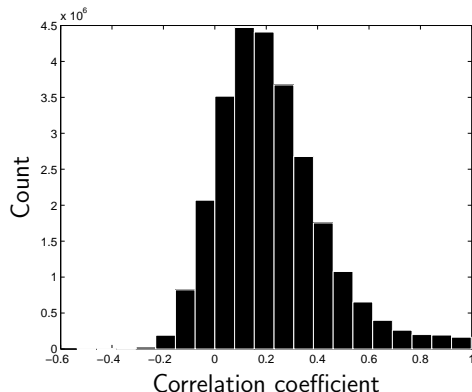


Figure: Histogram of the $M(M - 1)/2$ correlation coefficients between different images in the database.



Prediction performance

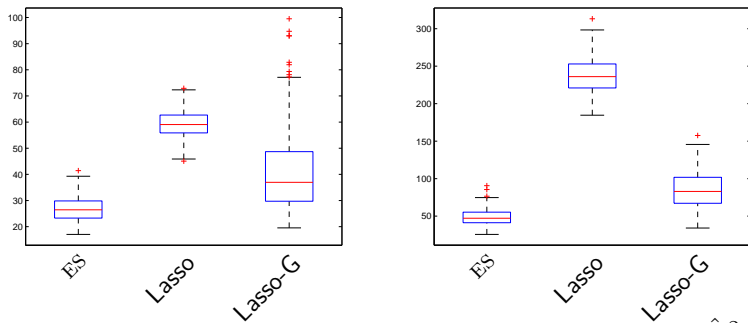


Figure: *Left:* Boxplots of the predictive performance $|\mu - \mathbf{X}\hat{\theta}|_2^2$ of the ES, Lasso and Lasso-Gauss (Lasso-G) estimators computed from 250 replications. *Left:* $\sigma = 0.5$. *Right:* $\sigma = 1$.



Examples of reconstructions

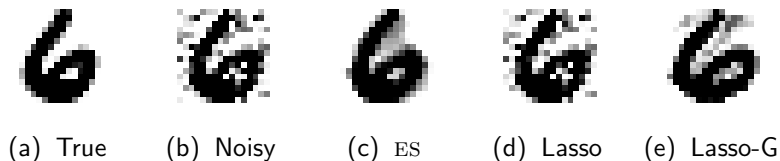


Figure: Reconstruction of the digit “6” with $\sigma = 0.5$

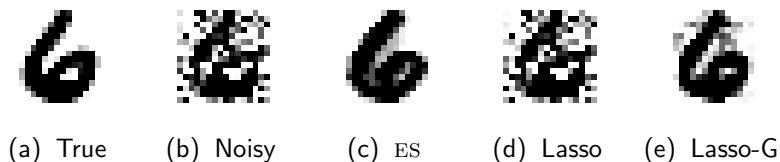
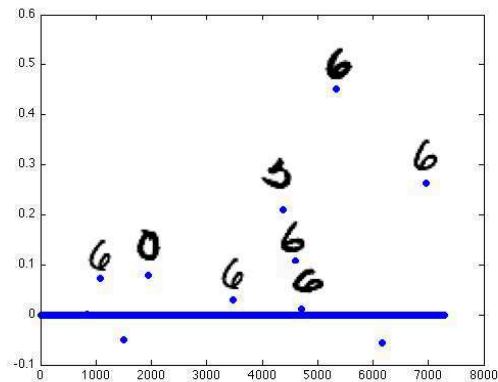


Figure: Reconstruction of the digit “6” with $\sigma = 1.0$



Interpretations of the coefficients in $\tilde{\theta}^{ES}$



Metropolis-Hastings on the cube

Set

$$\nu_{\mathbf{p}} \propto \exp\left(-\frac{1}{4\sigma^2} \sum_{i=1}^n (Y_i - f_{\hat{\theta}_{\mathbf{p}}}(x_i))^2\right) \pi_{\mathbf{p}}, \quad \mathbf{p} \in \mathcal{P}.$$

This Gibbs-type distribution can be expressed as the stationary distribution of the Markov chain generated by a Metropolis-Hastings algorithm. Consider the M -hypercube graph \mathcal{G} with vertices given by \mathcal{P} . For any $\mathbf{p} \in \mathcal{P}$, define the instrumental distribution $q(\cdot|\mathbf{p})$ as the uniform distribution on the neighbors of \mathbf{p} in \mathcal{G} .



Metropolis-Hastings on the cube

Fix $\mathbf{p}_0 = \mathbf{0} \in \mathbb{R}^M$. For any $t \geq 0$, given $\mathbf{p}_t \in \mathcal{P}$,

1. Generate a random variable Q_t with distribution $q(\cdot | \mathbf{p}_t)$.
2. Generate a random variable

$$P_{t+1} = \begin{cases} Q_t & \text{with probability } r(\mathbf{p}_t, Q_t) \\ \mathbf{p}_t & \text{with probability } 1 - r(\mathbf{p}_t, Q_t) \end{cases}$$

where

$$r(\mathbf{p}, \mathbf{q}) = \min \left(\frac{\nu_{\mathbf{q}}}{\nu_{\mathbf{p}}}, 1 \right).$$

3. Compute the least squares estimator $\hat{\theta}_{P_{t+1}}$.

