

Tensor Decomposition, Low Rank Structured Matrix Approximation and Applications

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Generalized Waring problem (1770)



Given a homogeneous polynomial T of degree d in the variables $\mathbf{x} = (x_0, x_1, \dots, x_n)$:

$$T(\mathbf{x}) = \sum_{|\alpha|=d} T_\alpha \mathbf{x}^\alpha,$$

find a minimal decomposition of T of the form

$$T(\mathbf{x}) = \sum_{i=1}^r \gamma_i (\zeta_{i,0}x_0 + \zeta_{i,1}x_1 + \dots + \zeta_{i,n}x_n)^d$$

for $\zeta_i = (\zeta_{i,0}, \zeta_{i,1}, \dots, \zeta_{i,n}) \in \mathbb{C}^{n+1}$, $\gamma_i \in \mathbb{C}$.

The minimal r in such a decomposition is called the **rank** of T .

Geometric point of view

Definition (Veronese variety)

$$\begin{aligned}\nu_d : \mathbb{P}(E) &\rightarrow \mathbb{P}(S^d(E)) \\ [\mathbf{v}] &\mapsto [\mathbf{v}(\mathbf{x})^d]\end{aligned}$$

Its image is the **Veronese** variety, denoted $\chi_1(S^d(E))$.

Definition (Secant of the Veronese variety)

$$\begin{aligned}\chi_r^{0,d} &= \{[T] \in \mathbb{P}(S^d) \mid \exists \mathbf{w}_1, \dots, \mathbf{w}_r \in \chi_1(S^d(E)) \text{ s.t. } T = \sum_{i=1}^r \mathbf{w}_i\} \\ \chi_r^d &= \overline{\chi_r^{0,d}}\end{aligned}$$

- ↪ $r(T)$ = smallest r s.t. $T \in \chi_r^{0,d}$, called the **rank** of T .
- ↪ $r_\sigma(T)$ = smallest r s.t. $T \in \chi_r^d$, called the **border rank** of T .

Example: $T_\epsilon := \frac{1}{d\epsilon} ((x_0 + \epsilon x_1)^d - x_0^d)$, $T_0 := x_0^{d-1} x_1$.
 $r(T_\epsilon) = r_\sigma(T_0) = 2$ but $r(T_0) = d$.

Algebraic point of view

Apolar product: For $f = \sum_{|\alpha|=d} f_\alpha \binom{d}{\alpha} \mathbf{x}^\alpha$, $g = \sum_{|\alpha|=d} g_\alpha \binom{d}{\alpha} \mathbf{x}^\alpha \in S^d$,

$$\langle f, g \rangle = \sum_{|\alpha|=d} f_\alpha g_\alpha \binom{d}{\alpha}.$$

For homogeneous polynomials $g(x_0, \dots, x_n)$ of degree d and $\mathbf{k}(\mathbf{x}) = \mathbf{k}_0 x_0 + \dots + \mathbf{k}_n x_n$,

$$\langle g(\mathbf{x}), \mathbf{k}(\mathbf{x})^d \rangle = g(\mathbf{k}_0, \dots, \mathbf{k}_n) = g(\mathbf{k}).$$

👉 If $T = \mathbf{k}_1(\mathbf{x})^d + \dots + \mathbf{k}_r(\mathbf{x})^d$ and $g(\mathbf{k}_i) = 0$ for $i = 1, \dots, r$, then $\forall h$ with $\deg(h) = d - \deg(g)$

$$\langle g h, T \rangle = 0.$$

👉 Find the polynomials apolar to T and compute their roots.

Algebraic point of view

$$S := \mathbb{K}[x_0, \dots, x_n]; S^d := \{f \in S; \deg(f) = d\};$$

Definition (Apolar ideal)

$$(T^\perp) = \{g \in S \mid \forall h \in S^{d-\deg(g)}, \langle g h, T \rangle = 0\} \supset S^{d+1}.$$

Problem: find an ideal $I \subset S$ such that

- ▶ $I \subset (T^\perp)$;
- ▶ I is saturated zero dimensional;
- ▶ I defines a minimal number r of simple points.

👉 necessary and sufficient conditions that T is of rank r .

Sylvester approach (1886)



Theorem

The binary form $T(x_0, x_1) = \sum_{i=0}^d t_i \binom{d}{i} x_0^{d-i} x_1^i$ can be decomposed as a sum of r distinct powers of linear forms

$$T = \sum_{k=1}^r \lambda_k (\alpha_k x_0 + \beta_k x_1)^d$$

iff there exists a polynomial q such that

$$\begin{bmatrix} t_0 & t_1 & \dots & t_r \\ t_1 & & & t_{r+1} \\ \vdots & & & \vdots \\ t_{d-r} & \dots & t_{d-1} & t_d \end{bmatrix} \begin{bmatrix} q_0 \\ q_1 \\ \vdots \\ q_r \end{bmatrix} = 0$$

and of the form $q(x_0, x_1) := \mu \prod_{k=1}^r (\beta_k x_0 - \alpha_k x_1)$.

Interpolation point of view

For $T = T(\mathbf{x}) = \sum_{\substack{\alpha \in \mathbb{N}^n; \\ |\alpha| \leq \delta}} T_\alpha \mathbf{x}^\alpha \in \mathcal{T}$, let

$T^*(\mathbf{d}) = \sum_{\substack{\alpha \in \mathbb{N}^n; \\ |\alpha| \leq \delta}} (\delta - |\alpha|)^{-1} T_\alpha \mathbf{d}^\alpha \in R^* = \mathbb{K}[[\mathbf{d}]]$ such that $\forall T' \in R_\delta$,

$$\langle T | T' \rangle = T^*(T').$$

Property: Given $T \in R_\delta$, find $\gamma_i \neq 0, \zeta_i \in \mathbb{K}^n, i = 1, \dots, r$, such that

$$T = \sum_{i=1}^r \gamma_i \langle \zeta_i, \mathbf{x} \rangle^d$$

iff

$$T^* \equiv \sum_{i=1}^r \gamma_i \mathbf{1}_{\zeta_i}.$$

on R_δ .

Flat extension point of view

Flattening map ϕ : For $\mathbf{x}^A \subset R$, $B, B' \subset A$ with $B \cdot B' \subset A$, and $\Lambda := T^* \in \langle \mathbf{x}^A \rangle^*$: $p = \sum_{\alpha \in A} p_\alpha \mathbf{x}^\alpha \mapsto \sum_{\alpha \in A} p_\alpha T_\alpha$, we define

$$H_{T^*}^{B', B} : \langle \mathbf{x}^{B'} \rangle \rightarrow \langle \mathbf{x}^B \rangle^*$$
$$p = \sum_{\beta \in B'} p_\beta \mathbf{x}^\beta \mapsto p \cdot T^*$$

with $p \cdot \Lambda : q \in \langle B \rangle \mapsto T^*(pq) = \langle T, pq \rangle \in \mathbb{K}$.

Its matrix is $H_T^{B', B} := [T_{\beta'+\beta}]_{\beta' \in B', \beta \in B}$.

Problem: Given $T^* \in R_\delta^*$, find $\tilde{\Lambda} \in R^*$ such that

$$H_{\tilde{\Lambda}} : R \rightarrow R^*$$
$$p \mapsto p \cdot \tilde{\Lambda}$$

- ▶ extends $H_{T^*}^{B, B'}$
- ▶ has minimal rank and
- ▶ $I_{\tilde{\Lambda}} = \ker H_{\tilde{\Lambda}}$ is a radical ideal.

Flat extension

$B^+ = B \cap x_1 B \cap \dots \cap x_n B$. B connected to 1 if $b \in B$ is either 1 or $x_{i_0} b'$, $b' \in B$.

Theorem (LM'09, BCMT'10, BBCM'11)

Let B, B' be connected to 1 of size r , E, E' connected to 1 with $B^+ \subset E$, $B'^+ \subset E'$ and $\Lambda \in \langle E \cdot E' \rangle^*$. The following conditions are equivalent:

- 1 there exists a unique element $\tilde{\Lambda} \in R^*$ which extends Λ and such that B and B' are basis of $\mathcal{A}_\Lambda = R/I_\Lambda$.
- 2 $\text{rank} H_\Lambda^{E, E'} = \text{rank} H_\Lambda^{B, B'} = r$.
- 3 $H_\Lambda^{B, B'}$ is invertible and the matrices $M_i := H_\Lambda^{B, x_i B'} (H_\Lambda^{B, B'})^{-1}$ satisfy

$$M_i \circ M_j = M_j \circ M_i \quad (1 \leq i, j \leq n).$$

In this case,

- ▶ $I_\Lambda = (\ker H_\Lambda^{E, E'})$,
- ▶ $\tilde{\Lambda}$ is supported on the points $\mathcal{V}_\Lambda^{\mathbb{C}} = \mathcal{V}^{\mathbb{C}}(I_\Lambda) = \{\zeta_1, \dots, \zeta_{r'}\}$ with $r' < r$.

Recovering the decomposition

If the flat extension problem has a solution $\tilde{\Lambda}$, then:

- ▶ $r = \text{rank} H_{\tilde{\Lambda}} = \dim R/(\ker H_{\tilde{\Lambda}})$ where $r = |B| = |B'|$;
- ▶ Let B, B' be maximal sets of monomials $\subset R$ s.t. $H_{\tilde{\Lambda}}^{B',B}$ invertible, then

$$M_i^{B',B} := H_{\tilde{\Lambda}}^{B',x_i B} (H_{\tilde{\Lambda}}^{B',B})^{-1}.$$

is the matrix of multiplication by x_i in $\mathcal{A}_{\tilde{\Lambda}} = R/(\ker H_{\tilde{\Lambda}})$.

- ▶ If the decomposition is of size r , the eigenvectors of the operators $(M_i^t)_i$ are simple and equal (up to scalar) to $\{\mathbf{1}_{\zeta_1}, \dots, \mathbf{1}_{\zeta_r}\}$.
- ▶ $\ker H_{\tilde{\Lambda}} = (\ker H_{\tilde{\Lambda}}^{B^+,B^+})$ where $B^+ = B \cup x_1 B \cup \dots \cup x_n B$;
- ▶ For each $x^\alpha \in \partial B = B^+ \setminus B$, there exists a unique

$$f_\alpha = x^\alpha - \sum_{\beta} z_{\alpha,\beta} x^\beta \in \ker H_{\tilde{\Lambda}}^{B^+,B^+}.$$

The $(f_\alpha)_{\alpha \in \partial B}$ form a **border basis** of $I_{\tilde{\Lambda}} = \ker H_{\tilde{\Lambda}}$ with respect to B .

Example in $\chi_6(S^4(\mathbb{K}^3))$

The tensor:

$$T = 79 x_0 x_1^3 + 56 x_0^2 x_2^2 + 49 x_1^2 x_2^2 + 4 x_0 x_1 x_2^2 + 57 x_0^3 x_1.$$

The 15×15 Hankel matrix:

	1	x_1	x_2	x_1^2	$x_1 x_2$	x_2^2	x_1^3	$x_1^2 x_2$	$x_1 x_2^2$	x_2^3	x_1^4	$x_1^3 x_2$	$x_1^2 x_2^2$	$x_1 x_2^3$	x_2^4
1	0	$\frac{57}{4}$	0	0	0	$\frac{28}{3}$	$\frac{79}{4}$	0	$\frac{1}{3}$	0	0	0	$\frac{49}{6}$	0	0
x_1	$\frac{57}{4}$	0	0	$\frac{79}{4}$	0	$\frac{1}{3}$	0	0	$\frac{49}{6}$	0	h_{500}	h_{410}	h_{320}	h_{230}	h_{140}
x_2	0	0	$\frac{28}{3}$	0	$\frac{1}{3}$	0	0	$\frac{49}{6}$	0	0	h_{410}	h_{320}	h_{230}	h_{140}	h_{050}
x_1^2	0	$\frac{79}{4}$	0	0	0	$\frac{49}{6}$	h_{500}	h_{410}	h_{320}	h_{230}	h_{600}	h_{510}	h_{420}	h_{330}	h_{240}
$x_1 x_2$	0	0	$\frac{1}{3}$	0	$\frac{49}{6}$	0	h_{410}	h_{320}	h_{230}	h_{140}	h_{510}	h_{420}	h_{330}	h_{240}	h_{150}
x_2^2	$\frac{28}{3}$	$\frac{1}{3}$	0	$\frac{49}{6}$	0	0	h_{320}	h_{230}	h_{140}	h_{050}	h_{420}	h_{330}	h_{240}	h_{150}	h_{060}
x_1^3	$\frac{79}{4}$	0	0	h_{500}	h_{410}	h_{320}	h_{600}	h_{510}	h_{420}	h_{330}	h_{700}	h_{610}	h_{520}	h_{430}	h_{340}
$x_1^2 x_2$	0	0	$\frac{49}{6}$	h_{410}	h_{320}	h_{230}	h_{510}	h_{420}	h_{330}	h_{240}	h_{610}	h_{520}	h_{430}	h_{340}	h_{250}
$x_1 x_2^2$	$\frac{1}{3}$	$\frac{49}{6}$	0	h_{320}	h_{230}	h_{140}	h_{420}	h_{330}	h_{240}	h_{150}	h_{520}	h_{430}	h_{340}	h_{250}	h_{160}
x_2^3	0	0	0	h_{230}	h_{140}	h_{050}	h_{330}	h_{240}	h_{150}	h_{060}	h_{430}	h_{340}	h_{250}	h_{160}	h_{070}
x_1^4	0	h_{500}	h_{410}	h_{600}	h_{510}	h_{420}	h_{700}	h_{610}	h_{520}	h_{430}	h_{800}	h_{710}	h_{620}	h_{530}	h_{440}
$x_1^3 x_2$	0	h_{410}	h_{320}	h_{510}	h_{420}	h_{330}	h_{610}	h_{520}	h_{430}	h_{340}	h_{710}	h_{620}	h_{530}	h_{440}	h_{350}
$x_1^2 x_2^2$	$\frac{49}{6}$	h_{320}	h_{230}	h_{420}	h_{330}	h_{240}	h_{520}	h_{430}	h_{340}	h_{250}	h_{620}	h_{530}	h_{440}	h_{350}	h_{260}
$x_1 x_2^3$	0	h_{230}	h_{140}	h_{330}	h_{240}	h_{150}	h_{430}	h_{340}	h_{250}	h_{160}	h_{530}	h_{440}	h_{350}	h_{260}	h_{170}
x_2^4	0	h_{140}	h_{050}	h_{240}	h_{150}	h_{060}	h_{340}	h_{250}	h_{160}	h_{070}	h_{440}	h_{350}	h_{260}	h_{170}	h_{080}

Extract a (6×6) principal minor of full rank:

$$H_{\Lambda}^B = \begin{bmatrix} 0 & \frac{57}{4} & 0 & 0 & 0 & \frac{28}{3} \\ \frac{57}{4} & 0 & 0 & \frac{79}{4} & 0 & \frac{1}{3} \\ 0 & 0 & \frac{28}{3} & 0 & \frac{1}{3} & 0 \\ 0 & \frac{79}{4} & 0 & 0 & 0 & \frac{49}{6} \\ 0 & 0 & \frac{1}{3} & 0 & \frac{49}{6} & 0 \\ \frac{28}{3} & \frac{1}{3} & 0 & \frac{49}{6} & 0 & 0 \end{bmatrix}$$

The columns (and the rows) of the matrix correspond to the monomials $\{1, x_1, x_2, x_1^2, x_1x_2, x_2^2\}$.

The shifted matrix $H_{x_1 \cdot \Lambda}^{B,B}$ is

$$H_{x_1 \cdot \Lambda}^{B,B} = H_{\Lambda}^{B, x_1 B} = \begin{bmatrix} \frac{57}{4} & 0 & 0 & \frac{79}{4} & 0 & \frac{1}{3} \\ 0 & \frac{79}{4} & 0 & 0 & 0 & \frac{49}{6} \\ 0 & 0 & \frac{1}{3} & 0 & \frac{49}{6} & 0 \\ \frac{79}{4} & 0 & 0 & h_{500} & h_{410} & h_{320} \\ 0 & 0 & \frac{49}{6} & h_{410} & h_{320} & h_{230} \\ \frac{1}{3} & \frac{49}{6} & 0 & h_{320} & h_{230} & h_{140} \end{bmatrix}$$

The columns of the matrix correspond to the monomials

$$\{x_1, x_1^2, x_1 x_2, x_1^3, x_1^2 x_2, x_1 x_2^2\} = \{1, x_1, x_2, x_1^2, x_1 x_2, x_2^2\} \times x_1.$$

Similarly,

$$H_{x_2 \cdot \Lambda}^{B,B} = H_{\Lambda}^{B, x_2 B} = \begin{bmatrix} 0 & 0 & \frac{28}{3} & 0 & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{3} & 0 & \frac{49}{6} & 0 \\ \frac{28}{3} & \frac{1}{3} & 0 & \frac{49}{6} & 0 & 0 \\ 0 & 0 & \frac{49}{6} & h_{410} & h_{320} & h_{230} \\ \frac{1}{3} & \frac{49}{6} & 0 & h_{320} & h_{230} & h_{140} \\ 0 & 0 & 0 & h_{230} & h_{140} & h_{050} \end{bmatrix}$$

We form (all) the possible matrix equations:

$$M_{x_i} M_{x_j} - M_{x_j} M_{x_i} = H_{x_1 \cdot \Lambda} H_{\Lambda}^{-1} H_{x_2 \cdot \Lambda} H_{\Lambda}^{-1} - H_{x_2 \cdot \Lambda} H_{\Lambda}^{-1} H_{x_1 \cdot \Lambda} H_{\Lambda}^{-1} = 0.$$

Many of the resulting equations are trivial. We have 6 unknowns: $h_{500}, h_{410}, h_{320}, h_{230}, h_{140}, h_{050}$ and 15 non-trivial equations.

A solution of the system is:

$$h_{500} = 1, h_{410} = 2, h_{320} = 3, h_{230} = 1.5060, h_{140} = 4.960, h_{050} = 0.056.$$

We substitute these values to $H_{x_1 \cdot \Lambda}$ and solve the generalized eigenvalue problem $(H_{x_1 \cdot \Lambda} - \zeta H_{\Lambda}) \mathbf{v} = 0$. The normalized eigenvectors are

$$\begin{bmatrix} 1 \\ -0.830 + 1.593 i \\ -0.326 - 0.0501 i \\ -1.849 - 2.645 i \\ 0.350 - 0.478 i \\ 0.103 + 0.0327 i \end{bmatrix}, \begin{bmatrix} 1 \\ -0.830 - 1.593 i \\ -0.326 + 0.050 i \\ -1.849 + 2.645 i \\ 0.350 + 0.478 i \\ 0.103 - 0.032 i \end{bmatrix}, \begin{bmatrix} 1 \\ 1.142 \\ 0.836 \\ 1.305 \\ 0.955 \\ 0.699 \end{bmatrix},$$

$$\begin{bmatrix} 1 \\ 0.956 \\ -0.713 \\ 0.914 \\ -0.682 \\ 0.509 \end{bmatrix}, \begin{bmatrix} 1 \\ -0.838 + 0.130 i \\ 0.060 + 0.736 i \\ 0.686 - 0.219 i \\ -0.147 - 0.610 i \\ -0.539 + 0.089 i \end{bmatrix}, \begin{bmatrix} 1 \\ -0.838 - 0.130 i \\ 0.060 - 0.736 i \\ 0.686 + 0.219 i \\ -0.147 + 0.610 i \\ -0.539 - 0.089 i \end{bmatrix}.$$

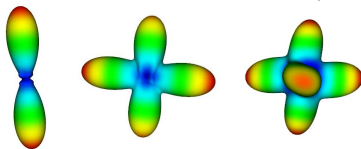
As the coordinates of the eigenvectors correspond to the evaluations of $\{1, x_1, x_2, x_1^2, x_1 x_2, x_2^2\}$, we can recover the values of (x_1, x_2) .

After solving the over-constrained linear system obtained by expansion and looking coefficient-wise, we deduce the decomposition:

$$\begin{aligned}
 & (0.517 + 0.044 i) (x_0 - (0.830 - 1.593 i)x_1 - (0.326 + 0.050 i)x_2)^4 \\
 & + (0.517 - 0.044 i) (x_0 - (0.830 + 1.593 i)x_1 - (0.326 - 0.050 i)x_2)^4 \\
 & \quad + 2.958 (x_0 + (1.142)x_1 + 0.836x_2)^4 \\
 & \quad + 4.583 (x_0 + (0.956)x_1 - 0.713x_2)^4 \\
 & - (4.288 + 1.119 i) (x_0 - (0.838 - 0.130 i)x_1 + (0.060 + 0.736 i)x_2)^4 \\
 & - (4.288 - 1.119 i) (x_0 - (0.838 + 0.130 i)x_1 + (0.060 - 0.736 i)x_2)^4
 \end{aligned}$$

Recovering branching structures

- ▶ At points, perform directional measurements (of water diffusion):

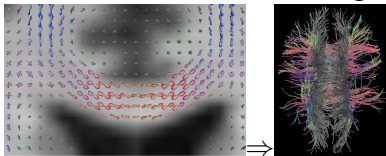


- ▶ Approximate the set of measurements on the sphere by a (symmetric) tensor $T = (T_{i,j,k,l})$.
- ▶ Decompose/approximate it as a minimal sum of tensors of rank 1:

$$T = \sum_{i=1}^r \lambda_i v_i^4.$$

to identify the main directions of diffusion.

- ▶ From the decomposition of tensors, deduce the geometric structure:



cf. [T. Schultz, H.P. Seidel'08], [A. Ghosh, R. Deriche, ...'09]

Concluding remarks/questions

- ▶ What about **nearest r -decomposition(s)** and SVD-like properties ?
- ▶ Applies to **multi-symmetric** tensors. Can we extend it to **anti-symmetric** tensors ?
- ▶ Can we extend it to minimal decomposition **over the real** ? to minimal **positive** decomposition ?

Collaborators: A. Bernardi, J. Brachat, P. Comon, M. Dien, E. Tsigaridas.

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Thanks for your attention